#### CMOS 8-Bit Microcontroller

## TMP88CH47N, TMP88CH47F

TMP88CH47N is high-speed and high-function 8-bit single-chip microcomputers whose built-in features include large-capacity RAM, multi-function timer/counter, and 10-bit AD converter, serial interface (UART/I2C bus). They are equipped with 3 phase brushless DC sensorless/sensor motor control, and AC motor inverter control.

Part No.	ROM	RAM	Package	OTP MCU
TMP88CH47N	16K bytes	E12 by dag	P-SDIP42-600-1.78	TMP88PH47N
TMP88CH47F	Tok bytes	512 bytes	P-QFP-1414-0.80D	TMP88PH47F

#### **Features**

- ▶8-bit single-chip microcomputer TLCS-870/X series microcomputer
- Interrupt sources: 23 (5 external, 18 Internal)
- ◆I/O ports: 34 pins
  - Large-current output: 8 pins (typ. 20 mA), LED direct drive
- ▶ 16-bit timer/counter: 2 channels
  - Timer, event counter, programmable pulse generator (PPG) output, pulse width measurement, external trigger timer, window mode
- ◆8-bit Timer/Counter: 1 channel
  - Timer capture (pulse width measurement), programmable divider output (PDO) mode
- ◆Time base timer (interrupt frequency: 1 to 16384 Hz)
- ◆Watchdog timer
- Divider output function (frequency: 1 to 8 kHz)
- Programmable motor driver (PMD): 1 channel
  - Rotor position: minimum resolution of 250 ns for detecting rotor position
  - Motor control timer, timer capture function
  - Overload protection function DC overload protection function AC overload protection function
    - (Can halt counter in 3-phase PWM output circuit)
  - Protection circuit for malfunction (urgent halt)
  - Automatic direction change, automatic position detection start
- Serial interface
  - 8-bit SIO/I<sup>2</sup>C bus
  - Universal asynchronous receiver transmitter (UART)
- 10-bit successive approximation type AD converter
  - Analog input: 8 channels
  - Conversion time: 11.5  $\mu$ s/46  $\mu$ s (at 16 MHz operation)
- Low power dissipation operation (2 modes)
  - STOP mode: Stops oscillation (battery or capacitor backup). Port output hold or high impedance selectable
  - IDLE mode: Stops CPU but continues operation of peripheral hardware. Released by interrupt (restarts CPU)
- ◆Operating voltage: 4.5 to 5.5 V at 16 MHz operation

980910EBP2

TMP88CH47N

TMP88PH47N

TMP88CH47F

TMP88PH47F

- 980910EBP2

  For a discussion of how the reliability of microcontrollers can be predicted, please refer to Section 1.3 of the chapter entitled Quality and Reliability Assurance/Handling Precautions.

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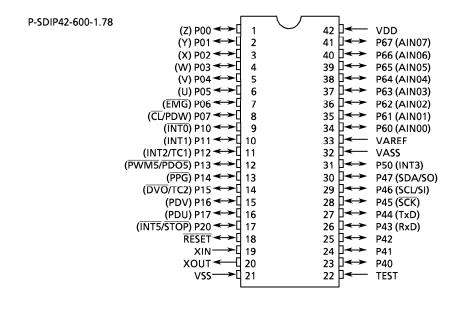
Purchase of TOSHIBA I<sup>2</sup> C components conveys a license under the Philips I<sup>2</sup> C Patent Rights to use these components in an I<sup>2</sup> C system, provided that the system conforms to the I<sup>2</sup> C Standard Specification as defined by Philips.

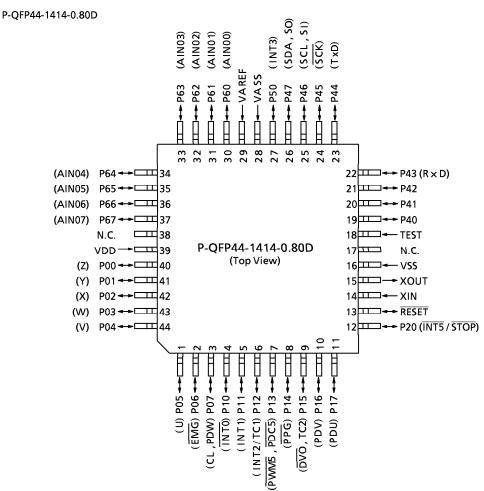
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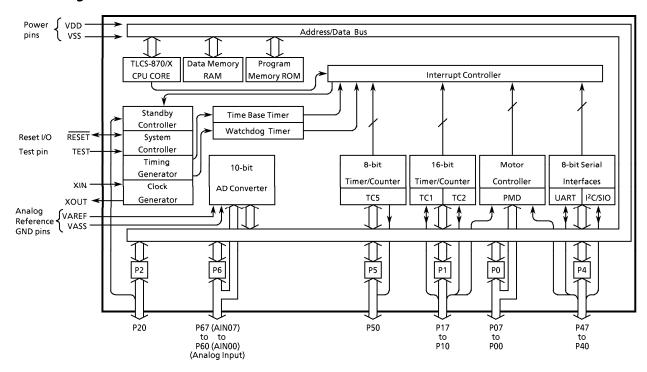
P-QFP44-1414-0.80D

## **Pin Assignments**





### **Block Diagram**



# **Pin Function**

Pin Name	1/0	Fun	ction
P07 (CL/PDW)	W2 (1)	8-bit programmable I/O port (tri state) Input or output specifiable in units of	Overload protection input /motor control circuit W-phase position detection input
P06 (E <u>MG</u> )	··· I/O (Input)	bits.  When using pins for motor control	Motor control circuit malfunction detection input
P05 (U)		circuit, set accordingly using POCR, then MDCR to 1.	Motor control circuit U-/V-/W-phase
P04 (V)	I/O (Output)		output
P03 (W)			
P02 (X)			Motor control circuit X-/ Y-/Z-phase output
P01 (Y)	I/O (Output)		datpat
P00 (Z)			
P17 (PDU)	W2 (1)	8-bit programmable I/O port (tri state) Input or output specifiable units of bits.	Motor control circuit U-phase position detection input
P16 (PDV)	··· I/O (Input)	When using pins for motor control circuit, timer/counter input, or external	Motor control circuit V-phase position detection input
P15 (DVO/TC2)	II/O (Output/Input)	interrupt input, set them to input mode.	Divider output or Timer/Counter 2 input
P14 (PPG)		When using pins for PPG output, divider output, or PWM output/PDO output, set	Programmable pulse generator output
P13 (PWM5/PDO5)	··· I/O (Output)	them to output mode.	PWM5 output/PDO5 output
D12 (INIT2/TC1)			External interrupt input 2 or
P12 (INT2/TC1)	I/O (Input)		Timer/Counter 1 input
P11 (INT1)			External interrupt input 1
P10 ( <del>INT0</del> )			External interrupt input 0

Pin Name	1/0	Fun	ction		
P20 (INT5/STOP)	I/O (Input)	1-bit I/O port When using pins for input port, external interrupt input, or STOP mode release input, set output latches to 1.	External interrupt input 5 or STOP mode release signal input		
P47 (SDA/SO)	I/O (I/O/Output)	8-bit I/O port			
P46 (SCL/SI)	I/O (I/O/Input)	When using pins for motor control	12C/SIO I/O		
P45 (SCK)	I/O (I/O)	circuit input, UART/I <sup>2</sup> C/SIO, set output latches to 1.			
P44 (TxD)	I/O (Input)	lateries to 1.	UART data input		
P43 (RxD)	I/O (Output)		UART data output		
P42			_		
P41	1/0		_		
P40			<u> </u>		
P50 (INT3)	I/O (Input)	1-bit input/output port with latch. When using pins for input port, HPWM output, PWM output/PDO output, external interrupt input, or timer/counter input, set output latches to 1.	External interrupt 3 input		
P67 (AIN07) to P60 (AIN00)	I/O (Input)	8-bit programmable I/O port (tri state) Input or output specifiable in units of bits.  When using pins for analog input, set to input mode using P6CR and ADCCR.	AD converter analog input		
XIN, XOUT	Input, Output	High-frequency oscillator connecting pins and leave XOUT open.	. For external clock input, input to XIN		
RESET	I/O	Reset signal input, watchdog timer output, address trap reset output, system clock reset output			
TEST	Input	Shipment test pin. Fix to "L" level.			
VDD, VSS	Danier Court	+ 5 V, 0 V (GND)			
VAREF, VASS	Power Supply	Analog reference voltage for AD conversion. Reference GND.			

#### **Operation**

### 1. CPU Core Functions

The CPU core consists of the CPU, system clock control circuit, and interrupt control circuit. This chapter describes the CPU core, program memory, data memory and the reset circuit.

#### 1.1 Memory Address Map

The TMP88CH47 memory consists of four blocks: ROM, RAM, special function registers (SFR) and Data buffer registers (DBR). They are all mapped to a 1M-byte address space. Figure 1-1 shows the TMP88CH47 memory address map. There are 16 general-purpose registers mapped to the RAM address space.

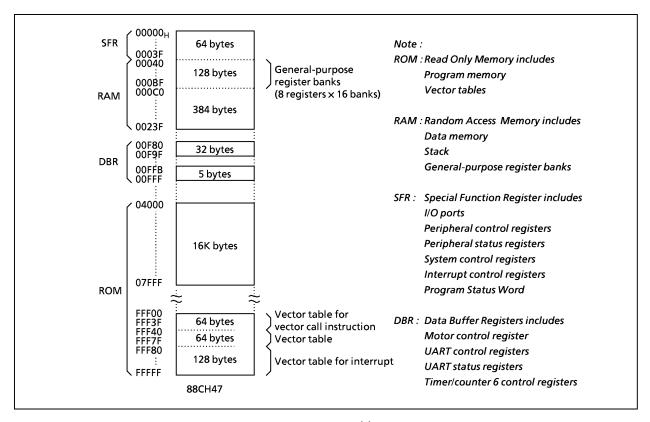


Figure 1-1. Memory Address Maps

### 1.2 Program Memory (ROM)

TMP88CH47 contains a 16K-byte program memory (mask ROM) at addresses from 04000 to 07FFF<sub>H</sub>. In addition, contains a 256-byte program memory (mask ROM) at addresses from FFF00 to FFFFF<sub>H</sub>.

#### **Electrical Characteristics**

Absolute Maximum Ratings  $(V_{SS} = 0 V)$ 

Parameter	Symbol	Pins	Ratings	Unit
Supply Voltage	$V_{DD}$		- 0.3 to 6.5	٧
Input Voltage	V <sub>IN</sub>		- 0.3 to V <sub>DD</sub> + 0.3	V
Output Valtana	V <sub>OUT1</sub>	Port P21, P22, RESET, Tri-state port	- 0.3 to V <sub>DD</sub> + 0.3	٧
Output Voltage	V <sub>OUT2</sub>	Port P20, Sink open drain port	– 0.3 to 5.5	٧
	I <sub>OUT1</sub>	Ports P1, P2, P4, P5, P6	3.2	
Output Current	I <sub>OUT2</sub>	Port P0	20	mA
	Σl <sub>OUT1</sub>	Ports P1, P2, P4, P5, P6	120	
Output Current	ΣΙ <sub>ΟUΤ2</sub>	Port P0	60	mA
Power Dissipation [Topr = 70°C]	PD	TMP88CH47	600	mW
Soldering Temperature (time)	Tsld		260 (10 s)	°C
Storage Temperature	Tstg		– 55 to 125	°C
Operating Temperature	Topr		- 40 to 85	°C

Note: The absolute maximum ratings are rated values which must not be exceeded during operation, even for an instant. Any one of the ratings must not be exceeded. If any absolute maximum rating is exceeded, a device may break down or its performance may be degraded, causing it to catch fire or explode resulting in injury to the user. Thus, when designing products which include this device, ensure that no absolute maximum rating value will ever be exceeded.

Recommended Opeating Conditions

 $(V_{SS} = 0 \text{ V}, \text{ Topr} = -40 \text{ to } 85^{\circ}\text{C})$ 

Parameter	Symbol	Pins	C	Conditions		Max	Unit
Supply Voltage	V <sub>DD</sub>			fc = NORMAL mode 16 MHz IDLE mode		5.5	V
				STOP mode			
	V <sub>IH1</sub>	Except hysteresis input	V >4.5V		V <sub>DD</sub> × 0.70		
Input High Voltage	V <sub>IH2</sub>	Hysteresis input	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	V <sub>DD</sub> ≥ 4.5 V V <sub>DD</sub> < 4.5 V		V <sub>DD</sub>	>
	V <sub>IH3</sub>		V				
	V <sub>IL1</sub>	Except hysteresis input		~		V <sub>DD</sub> × 0.30	
Input Low Voltage	V <sub>IL2</sub>	Hysteresis input	V	V <sub>DD</sub> ≧4.5 V		V <sub>DD</sub> × 0.25	V
	V <sub>IL3</sub>		V	V <sub>DD</sub> <4.5 V		V <sub>DD</sub> × 0.10	
Clock Frequency	fc	XIN, XOUT	V <sub>DD</sub> :	= 4.5 to 5.5 V	8.0	16.0	MHz

Note 1: The recommended operating conditions for a device are operating conditions under which it can be guaranteed that the device will operate as specified. If the device is used under operating conditions other than the recommended operating conditions (supply voltage, operating temperature range, specified AC/DC values etc.), malfunction may occur. Thus, when designing products which include this device, ensure that the recommended operating conditions for the device are always adhered to.

Note 2: Clock frequency fc: The condition of supply voltage range is the value in NORMAL and IDLE modes.

D.C. Characteristics

 $(V_{SS} = 0 \text{ V}, \text{ Topr} = -40 \text{ to } 85^{\circ}\text{C})$ 

Parameter	Symbol	Pins	Conditions	Min	Тур.	Max	Unit
Hysteresis Voltage	V <sub>HS</sub>	Hysteresis inputs		_	0.9	_	V
	I <sub>IN1</sub>	TEST					
Input Current	I <sub>IN2</sub>	Sink open drain, Tri-state ports	$V_{DD} = 5.5 \text{ V}$ $V_{IN} = 5.5 \text{ V/0 V}$	_	_	± 2	μΑ
	I <sub>IN3</sub>	RESET, STOP	VIN = 3.3 V/O V				
Local Bushes (#)	R <sub>IN</sub>	TEST with pull-down			70	170	
Input Resistor (*)		RESET		90	220	510	kΩ
Output Leakage Current	I <sub>OL</sub>	Sink open drain, Tri-state ports	V <sub>DD</sub> = 5.5 V, V <sub>OUT</sub> = 5.5 V/0 V	-	-	± 2	μΑ
Output High Voltage	V <sub>OH</sub>	Tri-state ports	$V_{DD} = 4.5 \text{ V}, \ I_{OH} = -0.7 \text{ mA}$	4.1	_	-	V
Outside Commit	I <sub>OL1</sub>	Except XOUT, Ports P0	$V_{DD} = 4.5 \text{ V}, \ \ V_{OL} = 0.4 \text{ V}$	_	1.6	_	
Output Low Current	I <sub>OL2</sub>	Port P0	V <sub>DD</sub> = 4.5 V, V <sub>OL</sub> = 1.0 V	_	10	_	mA
Supply Current in NORMAL Mode			V <sub>DD</sub> = 5.5 V	_	20	32	mA
Supply Current in IDLE Mode			$V_{IN} = 5.3 \text{ V}/0.2 \text{ V}$ fc = 16.0 MHz	_	10	16	mA
Supply Current in STOP Mode			$V_{DD} = 5.5 \text{ V}$ $V_{IN} = 5.3 \text{ V}/0.2 \text{ V}$	_	0.5	20	μΑ

Note 1: Typical values show those at Topr =  $25^{\circ}$ C,  $V_{DD} = 5 V$ .

Note 2: Input Current  $l_{IN1}$ ,  $l_{IN3}$ ; The current through registor is not included, when the input resistor (pull-up or pull-down)

is contained.

Note 3: IDD except I<sub>REF</sub>.

AD Conversion Characteristics

 $(Topr = -40 \text{ to } 85^{\circ}C)$ 

					Max			
Parameter	Symbol	Conditions	Min	Тур.	ADCDR1	ADC	ADCDR2	
					ADCDRI	ACK = 0	ACK = 1	
V <sub>ARE</sub>		., ., ., ., ., ., ., ., ., ., ., ., ., .	V <sub>DD</sub> – 1.0		V <sub>DD</sub>			
Analog Reference Voltage	V <sub>ASS</sub>	V <sub>AREF</sub> – V <sub>ASS</sub> ≧ 3.5 V	V <sub>SS</sub>	1		1.0		V
Analog Input Voltage	V <sub>AIN</sub>		V <sub>ASS</sub>	_		$V_{AREF}$		<b>&gt;</b>
Analog Supply Current	I <sub>REF</sub>	V <sub>AREF</sub> = 5.5 V, V <sub>ASS</sub> = 0.0 V	_	0.5		1.0		mA
Non-Linearity Error				1	± 1	± 3	± 2	
Zero Point Error		$V_{DD} = 5.0 \text{ V}, V_{SS} = 0.0 \text{ V}$	_	1	± 1	± 3	± 2	
Full Scale Error		V <sub>AREF</sub> = 5.000 V V <sub>ASS</sub> = 0.000 V	_	_	± 1	± 3	± 2	LSB
Total Error				_	± 2	± 6	± 4	

Note 1: ADCDR1: 8-bit AD conversion result (1LSB =  $\Delta V_{AREF}$ /256)

ADCDR2: 10-bit AD conversion result (1LSB =  $\Delta V_{AREF}$ /1024)

Note 2: Total error includes all errors except quantization error.

A.C. Characteristics

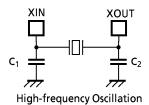
 $(V_{SS} = 0 \text{ V}, V_{DD} = 4.5 \text{ to } 5.5 \text{ V}, Topr = -40 \text{ to } 85^{\circ}\text{C})$ 

Parameter	Symbol	Conditions	Min	Тур.	Max	Unit
Machine Cycle Time	tov	NORMAL mode	0.25	-	0.5	. •
Machine Cycle Time	tcy	IDLE mode	0.25			μS
"H" Level Clock Pulse Width	t <sub>WCH</sub>	For external clock operation	31.25		62.5	ns
"L" Level Clock Pulse Width	t <sub>WCL</sub>	(XIN input)	31.23	1	02.5	115

**Recommended Oscillating Conditions** 

 $(V_{SS} = 0 \text{ V}, V_{DD} = 4.5 \text{ to } 5.5 \text{ V}, Topr = -40 \text{ to } 85^{\circ}\text{C})$ 

Parameter	Oscillator	Oscillation	Recommended Oscillator	Recommended Constant		
rarameter Oscillator		Frequency	Recommended Oscillator	C <sub>1</sub>	C <sub>2</sub>	
High-frequency Oscillation	Ceramic Resonator	16 MHz	MURATA CSA16.00 MXZ	5pF	5pF	
			MURATA CST16.00 MXW	built-in 5pF	built-in 5pF	



Note: An electrical shield by metal shield on the surface of IC package should be recommendable in order to prevent the device from the high electric fieldstress applied from CRT (Cathode Ray Tube) for continuous reliable operation.